Drink. Water Eng. Sci., 12, 1–13, 2019 https://doi.org/10.5194/dwes-12-1-2019 © Author(s) 2019. This work is distributed under the Creative Commons Attribution 4.0 License.



Analysis of water distribution network under pressure-deficient conditions through emitter setting

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Received: 23 August 2018 – Discussion started: 29 October 2018 Revised: 31 January 2019 – Accepted: 24 February 2019 – Published: 14 March 2019

Abstract. Pressure-driven analysis (PDA) of water distribution networks necessitates an assessment of the supplying capacity of a network within the minimum and required pressure ranges. Pressure-deficient conditions happen due to the uncertainty of nodal demands, failure of electromechanical components, diversion of water, aging of pipes, permanent increase in the demand at certain supply nodes, fire demand, etc. As the demanddriven analysis (DDA) solves the governing equations without any bound on pressure head, it fails to replicate the real scenario, particularly when the network experiences pressure-deficient situations. Numerous researchers formulated different head-discharge relations and used them iteratively with demand-driven software, while some other approaches solve them by incorporating this relation within the analysis algorithms. Several attempts have been made by adding fictitious network elements like reservoirs, check valves (CVs), flow control valves (FCVs), emitters, dummy nodes and pipes of negligible length (i.e., negligible pressure loss) to assess the supplying capability of a network under pressure-deficient conditions using demand-driven simulation software. This paper illustrates a simple way of assessing the supplying capacity of demand nodes (DNs) under pressuredeficient conditions by assigning the respective emitter coefficient only for those nodes facing a pressure-deficit condition. The proposed method is tested with three benchmark networks, and it is able to simulate the network without addition of any fictitious network elements or changing the source code of the software like EPANET. Though the proposed approach is an iterative one, the computational burden of adding artificial elements in the other methods is avoided and is hence useful for analyzing large networks.

1 Introduction

Analysis of water distribution systems under pressuredeficient conditions presents a challenging research area, as understanding and simulating the real scenario is complex. It is well known that demand-driven analysis (DDA) simultaneously solves the mass balance and energy balance equations to determine the flow in each pipe for a given network topology and configuration. However, such a DDA solution does not represent an exact behavior of the system when it is under pressure-deficient conditions or if a bound on service pressure is assigned (Ang and Jowitt, 2006; Siew and Tanyimboh, 2012; Suribabu, 2015). It is possible to notice the negative pressure in DDA whenever the total loss of the head occurring from the source to node exceeds the available source head. This mainly happens when the demand assigned to a node is higher than what the pipes incident to that node can actually carry based on the available source head. To compute the actual outflows from the nodes within given pres-



Figure 1. Interpretation of the nodal demand vs. head curve.

sure bounds, modifications are needed, either in the source code of a demand-driven simulation engine (e.g., Cheung et al., 2005) or by adding additional fictitious components like reservoirs, check valves (CVs), flow control valves (FCVs), emitters, dummy nodes and very short pipes to the demand nodes (DNs – e.g., Ozger, 2003; Ang and Jowitt, 2006; Rossman, 2007; Suribabu and Neelakantan, 2011; Jinesh Babu and Mohan, 2012; Gorev and Kodzhespirova, 2013; Sivakumar and Prasad, 2014, 2015; Morley and Tricarico, 2014; Abdy Sayyed et al., 2014, 2015; Suribabu, 2015; Suribabu et al., 2017; Mamizadeh and Sharoonizadeh, 2016; Mahmoud et al., 2017; Pacchin et al., 2017).

Mahmoud et al. (2017) addressed the shortcoming of each of these methods for evaluating outflow in the case of large networks and under extended-period simulation (EPS). They have developed a new way to handle PDA using EPANET in single-iterative type after an introduction of a check valve, a flow control valve and a flow emitter for both the steady state and EPS.

Pressure-driven analysis - literature review

In the beginning, the pressure-deficient condition was considered a rare phenomenon and/or a typical problem in an operational scenario. However, when concern on reliability gained importance, the failure scenarios were analyzed, and thus analysis of the pressure-deficient condition became popular. Two approaches are popular for analyzing the pressuredeficient condition. In the first approach a specific pressuredemand relationship is embedded in the source code of the simulator (requires changing of the source code). Some of the important studies by several authors using this approach are presented in tabular form below (Table 1).

Apart from the above research in the table, Liu et al. (2011) and Siew and Tanyimboh (2012) adopted different method-



Figure 2. Flow chart illustrating the computational steps involved in the proposed approach.



Figure 3. Layout of the two-loop network (example 1 and 2).

ologies to obtain node heads in EPANET. Giustolisi et al. (2011) developed and used new Excel-based software called WDNetXL. Generally, the limitations of this approach (Mahmoud et al., 2017) are that (1) it requires a change in algorithm and program code, (2) the computer codes are not available, (3) it requires iterations, (4) it is mostly demonstrated on sample networks, and (5) it exhibits difficulty in handling extended-period simulation.

Tal	ble	1.	Various	head-fl	ow rel	lations	hips	for	PDA.
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S1. no.	Author(s) and year	Head-flow equation	Remark
1	Bhave (1981)	$ \begin{array}{l} q_{j}^{\mathrm{avl}} = q_{j}^{\mathrm{req}} \; (\text{adequate flow}), \; \text{if } \; H_{j}^{\mathrm{avl}} \geq H_{j}^{\mathrm{min}} \\ 0 < q_{j}^{\mathrm{avl}} < q_{j}^{\mathrm{req}} \; (\text{partial flow}), \; \text{if } \; H_{j}^{\mathrm{min}} = H_{j}^{\mathrm{avl}} \\ q_{j}^{\mathrm{avl}} = 0 \; (\text{no flow}), \; \text{if } \; H_{j}^{\mathrm{avl}} \leq H_{j}^{\mathrm{min}} \end{array} \right\} $	First attempt for pressure-deficient analysis us- ing simultaneous head-flow equations along with energy and mass balance equations.
2	Germanopoulos (1985)	$q_j^{\text{avl}} = q_j^{\text{req}} \left(1 - 10^{-c_j [(H_j^{\text{avl}} - H_j^{\min})/(H_j^{\text{des}} - H_j^{\min})]} \right)$	C_j – node constant.
3	Wagner et al. (1988)	$ \left. \begin{array}{l} q_{j}^{\mathrm{avl}} = q_{j}^{\mathrm{req}}, \ \mathrm{if} \ H_{j}^{\mathrm{avl}} \geq H_{j}^{\mathrm{min}} \\ q_{j}^{\mathrm{avl}} = q_{j}^{\mathrm{req}} \left(\frac{H_{j}^{\mathrm{avl}} - H_{j}^{\mathrm{min}}}{H_{j}^{\mathrm{des}} - H_{j}^{\mathrm{min}}} \right)^{1/n}, \ \mathrm{if} \ H_{j}^{\mathrm{min}} < H_{j}^{\mathrm{avl}} < H_{j}^{\mathrm{des}} \\ q_{j}^{\mathrm{avl}} = 0, \ \mathrm{if} \ H_{j}^{\mathrm{avl}} \leq H_{j}^{\mathrm{min}} \end{array} \right\} $	n – exponent constant (its value often taken as either 1.85 or 2).
4	Reddy (1989) and Elango (1991)	$q_j^{\text{avl}} = S_j \left(H_j^{\text{avl}} - H_j^{\min} \right)^{0.5}$	S_j – node constant.
5	Chandapillai (1991)	$H_j^{\text{avl}} = H_j^{\min} + K_j \left(q_j^{\text{avl}} \right)^n$	K_j – constant; n – exponent.
6	Fujiwara and Ganesharajah (1993)	$ \begin{array}{l} q_{j}^{\mathrm{avl}} = q_{j}^{\mathrm{req}} \mbox{ for } H_{j}^{\mathrm{avl}} \geq H_{j}^{\mathrm{des}} \\ q_{j}^{\mathrm{avl}} = q_{j}^{\mathrm{req}} \left(\int_{H_{j}^{\mathrm{min}}(H_{j}^{\mathrm{avl}} - H_{j}^{\mathrm{min}})(H_{j}^{\mathrm{des}} - H_{j}^{\mathrm{avl}}) \mathrm{d}H} \\ \frac{H_{j}^{\mathrm{avl}}}{H_{j}^{\mathrm{avl}}(H_{j}^{\mathrm{avl}} - H_{j}^{\mathrm{min}})(H_{j}^{\mathrm{des}} - H_{j}^{\mathrm{avl}}) \mathrm{d}H} \\ q_{j}^{\mathrm{avl}} = 0 \mbox{ (no flow), if } H_{j}^{\mathrm{avl}} \leq H_{j}^{\mathrm{min}} \end{array} \right), \text{ if } H_{j}^{\mathrm{min}} < H_{j}^{\mathrm{avl}} < H_{j}^{\mathrm{des}} \\ \end{array} $	
7	Tucciarelli et al. (1999)	$ \begin{array}{l} q_j^{\mathrm{avl}} = q_j^{\mathrm{req}}, \ \mathrm{if} \ H_j^{\mathrm{avl}} \geq H_j^{\mathrm{min}} \\ q_j^{\mathrm{avl}} = q_j^{\mathrm{req}} \mathrm{sin}^2 \left(\frac{H_j^{\mathrm{avl}}}{H_j^{\mathrm{min}}} \right), \ \mathrm{if} \ 0 < H_j^{\mathrm{avl}} < H_j^{\mathrm{min}} \\ q_j^{\mathrm{avl}} = 0, \ \mathrm{if} \ H_j^{\mathrm{avl}} \leq 0 \end{array} \right\} $	
8	Tanyimboh et al. (2001)	Same as the equation of Wagner et al. (1988)	Drove Wagner's (1988) equation from Chan- dapillai (1991) equation. Using this attempted finding reliability of node as well as the net- work.
9	Wu et al. (2009)	$ \begin{array}{l} q_{j}^{\mathrm{avl}} = 0, \text{ if } H_{j}^{\mathrm{avl}} \leq 0 \\ q_{j}^{\mathrm{avl}} = q_{j}^{\mathrm{req}} \left(\frac{H_{j}^{\mathrm{avl}}}{H_{j}^{\mathrm{des}}}\right)^{1/n}, \text{ if } H_{j}^{\mathrm{avl}} < H_{j}^{\mathrm{thr}} \\ q_{j}^{\mathrm{avl}} = q_{j}^{\mathrm{req}} \left(\frac{H_{j}^{\mathrm{thr}}}{H_{j}^{\mathrm{des}}}\right)^{1/n}, \text{ if } H_{j}^{\mathrm{avl}} \geq H_{j}^{\mathrm{thr}} \end{array} \right\} $	H_j^{thr} – threshold pressure above which the demand is independent of nodal pressure.
10	Tanyimboh and Templeman (2010)	$q_j(H_j) = q_j^{\text{req}} \frac{\exp(\alpha_j + \beta_j H_j)}{1 + \exp(\alpha_j + \beta_j H_j)} \alpha_j = \frac{-4.595 H_j^{\text{des}} - 6.907 H_j^{\text{min}}}{H_j^{\text{des}} - H_j^{\text{min}}} \beta_j = \frac{11.502}{H_j^{\text{des}} - H_j^{\text{min}}}$	
11	Jun and Guoping (2013)	Considered-volume driven demand, pressure-driven demand and leaks.	Modified EPANET for nodal outflows based on pressure-dependent demand formulations and leakage models (EPANET-MNO).
12	Morley and Tri- carico (2014)	Modified source code of EPANET by introducing emitters.	Each emitter is assigned its own empirical ex- ponent. There are convergence issues when ap- plied to complex or larger water distribution networks.

Some of the researchers in the recent years attempted pressure-deficient analysis using EPANET (popular freeware demand-driven model) by introduction of a few artificial or imaginary components but without node head–flow relationships. This research claims a lower number of iterations, and the recent research claims single iteration (no iteration). The works using components in the demand-driven model for pressure-deficient analysis are presented in Table 2.

A literature review indicates that the approach of using a demand-driven engine to get the pressure-driven results is getting more attention. This is due to computational convenience and the promising trend of development. Hence, this research is also planned to focus on this approach. This paper proposes a simple approach to suit both the single period and EPS but without addition, deletion, opening and closing of network elements. The proposed method requires only assigning an emitter coefficient and altering nodal elevation by incorporating minimum pressure head with existing elevation. Though the method is an iterative type, it can be easily implemented, irrespective of the size of the network.

S. no.	Author(s) and year	Component used in demand-driven analy- sis	Remark
1	Ang and Jowitt (2006)	Artificial reservoir and artificial pipe at each node.	First (iterative) demand-driven application for pressure-deficient analysis. Popularly known as PDNA (pressure-deficient network algo- rithm).
2	Baek et al. (2010)	Nil.	Instead of iterative procedure, we used an opti- mization model. DDA model and head-flow relation- ships were also used.
3	Suribabu and Nee- lakantan (2011)	Artificial complementary reservoir and artificial pipe only at pressure-deficient nodes.	The approach used is known as CRS (comple- mentary reservoirs solution) method. Second author is the PI of this proposal.
4	Jinesh Babu and Mohan (2012)	Artificial reservoirs, artificial flow con- trol (to control flow to artificial reser- voirs), check valves (to avoid negative pressure) and artificial pipe at pressure- deficient nodes.	Demonstrated limitation of the Ang and Jowitt (2006) method. Reduced the number of iterations required significantly. Popularly known as modified PDNA (MPDNA).
5	Gorev and Kodzhespirova (2013)	Artificial reservoirs, artificial flow control valves, artificial check valves and addi- tional artificial pipes.	Results obtained in a single hydraulic run. Supports only parabolic type of node head–flow relationship.
6	Sivakumar and Prasad (2014)	Artificial reservoirs, artificial flow control valves, artificial check valves and artifi- cial pipe.	Highlighted limitations of the Ang and Jowitt (2006) method. Reduced the number of iterations required significantly. Could not simulate partial flow between the minimum and the desired pressure head levels.
7	Abdy Sayyed et al. (2013, 2014, 2015)	Replaced the artificial reservoir and artificial pipe with a flow emitter.	Works excellently for steady-state analysis. Did not consider minimum pressure head level.
8	Sivakumar and Prasad (2015)	Artificial reservoirs, artificial flow control valves, artificial check valves and addi- tional artificial pipes.	Compared MPDNA with different head–flow relationships. Proposed modifications to MPDNA. No need for iterative procedures.
9	Suribabu (2015)	Emitter.	Compared emitter-based PDA with other PDAs based on head-flow relations.
10	Mamizadeh and Sharoonizadeh (2016)	Among the two methods, in one method, the components added are same as in CRS approach of Suribabu and Neelakantan (2011). Added a flow control valve in another method.	Proposed two modified versions of CRS method (MCRS) to overcome certain drawbacks.
11	Sharoonizadeh et al. (2016)	Compared PDNA, MPDNA, CRS and MCRS methods.	Concluded that MPDNA and MCRS methods are better.
12	Suribabu et al. (2017)	Artificial reservoirs and artificial pipes.	Improved CRS method proposed.
13	Mahmoud et al. (2017)	Artificial check valve, artificial flow con- trol valve, artificial flow emitter, dummy node and artificial pipes at each pressure- deficient node.	Single-iteration pressure-driven analysis (SIPDA). Uses Wagner et al. (1988) node head–flow relationship.

Table 2. Use of artificial components in PDA.

2 Methodology

2.1 Background of emitter-based approaches

The EPANET 2 (Rossman, 2000) hydraulic simulation engine contains a special element called the emitter that behaves as a sprinkler head at the node and delivers an outflow proportional to the available pressure head. Rossman (2007) discussed the possibility of building the pressure-driven network analysis proposed by Ang and Jowitt (2006) in the EPANET hydraulic solver using this emitter feature. Furthermore, Suribabu (2015) proposed a method to use the emitter as a replacement to the connection of fictitious reservoirs to all the DNs. Here, the emitter determines the possible supply at all deficient nodes based on its available pressure head. The flow from the emitter is expressed as follows (Rossman, 2000):

$$Q = K_{\rm e} p^n, \tag{1}$$

where Q is nodal outflow, K_e is the emitter coefficient, n is the emitter exponent and p is pressure. Rossman (2007) suggested that the value of the emitter coefficient can be calculated according to the properties of the pipe that connects the node and the artificial reservoir (i.e., diameter, length and Hazen–Williams coefficient) in order to make it equivalent to the approach of Ang and Jowitt (2006). Another emitter-based approach was proposed by Abdy Sayyed et al. (2015), which is a non-iterative method by connecting a CV, an FCV and an emitter to the demand nodes. Furthermore, they have shown that the emitter equation is identical to that of Wagner (1988) for $H_j^{\text{req}} \ge H_j^{\min}$ if the emitter coefficient K_e and exponent γ are taken as follows:

$$K_{\rm e} = \frac{Q_j^{\rm req}}{\left(H_j^{\rm req} - H_j^{\rm Min}\right)^{\gamma}},\tag{2}$$

$$\gamma = \frac{1}{n_j},\tag{3}$$

where the nodal elevation of the emitter-set nodes is

$$NEL_j = EL_j + H_{\min}.$$
 (4)

Rossman (2000) also suggested that to get maximum flow at minimum pressure at demand nodes, the emitter coefficient shall be assigned to be 100 times the respective nodal demand. Hereafter it is referred to as K_{e100} (coefficient of discharge):

$$K_{e100} = 100 \times Q_j^{req}.$$
(5)

In Abdy Sayyed et al. (2015), the FCV is used to fulfill the maximum flow constraint, and the CV is employed to avoid flow reversal. Single-iteration pressure-driven analysis (SIPDA) proposed by Mohmoud et al. (2017) adopted



Figure 4. Layout of multisource pumped network (example 3).



Figure 5. Layout of Modena network (example 4).

the same sequence of network elements as that of the Abdy Sayyed et al. (2015) approach. But SIPDA adds the sequence of network elements and modifies their nodal elevations only for those nodes experiencing a pressure deficit. Pacchin et al. (2017) used another new sequence of elements (general purpose valve - GPV, CV and artificial reservoir) to evaluate outflow from the node under pressure-deficient conditions. Pacchin et al. (2017) applied the proposed approach and other similar methods to two real water distribution networks and concluded that their proposed method and that of Abdy Sayyed et al. (2015) are able to correctly produce the behavior of the network under pressure-deficient conditions. However, the drawback of these methodologies is the need to include two dummy nodes per node, which further increases the number of components and the topological complexity of the network. Though the addition of elements make it a



Figure 6. Actual outflow against design demand under no supply from reservoir ID 272 (LPS – liters per second).



Figure 7. Nodal pressure head under no component failure condition.

single snapshot analysis, its incorporation into each demand node makes the network too complex in topology. It consumes lot of time of the network modeler, unless a separate integrated component is created with a setting option in the existing software.

2.2 Assumptions

Many scientists (Bhave, 1981; Germanopoulos, 1985; Wagner et al., 1988; Reddy and Elango, 1989, 1991; Chandapillai, 1991; Fujiwara and Ganesharajah, 1993; Tucciarelli et al., 1999; Tanyimboh et al., 2001; Wu et al., 2009; Tanyimboh and Templeman, 2010) have suggested different head– flow relations for assessing the supplying capability of nodes under pressure-deficient conditions. Figure 1 presents an interpretation of the head–flow relations. Given the variables defined in Fig. 1, there are different assumptions that the modeler can make:

- The more general case is the one in which no assumption is made for Z, H_{\min} and H_{req} . In this case the minimum possible head on a node is its elevation Z, and if hydraulic conditions do not permit this, then the node is isolated, meaning not only that demand in the node must be zero but also that there is no flow in the adjacent pipes (i.e., no siphonic flow is considered). If the head is between Z and H_{\min} , then the demand at the node is still zero, but now flow in the adjacent pipes can happen if hydraulic conditions downstream permit it. If the head is between H_{\min} and H_{req} , then the demand at the node is only partially fulfilled even though the appliance or appliances are completely open; this is modeled with a transition curve which can take different forms (e.g, Germanopoulos, 1985; Bhave, 1989; Salgado-Castro, 1988; Wagner et al., 1988; Fujiwara and Li, 1998; Tanymboh and Templeman, 2010), although the Germanoupoulos (1985) emitter equation is commonly accepted as the most physically appropriate. If the head is above H_{req} , then the pressure in the appliance is enough to fulfill the required demand, and therefore the appliances are assumed to be partially closed to receive only the required demand; this means that a demand-driven analysis of the node is suitable.
- When Z < H is assumed (assuming that the actual junction elevation is below any possible value of H), this assumes that the water cannot ever reach the node isolation zone. Models that accept negative pressures in the system and flows downstream of these nodes are either making this assumption or assuming siphonic flow conditions (as long as the absolute pressure is above vapor pressure).</p>
- When $H_{\min} = Z$, this assumes that once there is some pressure in the node, there is some outflow. This assumption is valid when the node elevation actually represents the elevation of the lowest water demand appliance among all of the appliances lumped in it.
- When $H_{\text{req}} = H_{\text{min}}$, this assumes that once the head is above the minimum head (i.e., pressure in the emitter is above zero), the outflow is equal to the required flow or, when this condition is not met, the maximum flow hydraulically possible flow. This assumption can be modeled using the Rossman (2000) approximation of using an emitter coefficient of $100 \cdot Q_{\text{Reg}}$.

The method proposed in this study requires no assumptions of Z, H_{min} and H_{req} , although it can deal with any of the ones mentioned above. This means that the only assumptions made in the proposed pressure-driven analysis (PDA) are as follows:

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Figure 8. Nodal pressure when reservoir ID 272 is disconnected (DDA).

- Though available pressure is greater than required pressure, the outflow at demand nodes does not exceed its design demand. This is a very basic assumption made by municipal engineering at the project formulation stage.
- 2. No outflow is possible at demand node if available pressure is less than minimum service pressure.
- 3. Pressure-dependent outflow between required and minimum pressures takes the form shown in Fig. 1, and for the corresponding condition, the percentage of the valve opening is defined by the curve.
- 4. The water distribution network is considered a nonairtight system. Hence, no siphonic flow is possible in the network.
- 5. Emitter coefficient is considered based on either Eq. (2) or 100 times the nodal demand to estimate the outflow at minimum residual pressure (Eq. 5).

The present study proposes a simple approach by setting the emitter coefficient and changing the elevation of the nodes that have been identified as being pressure deficient through a few simulation runs of DDA. The proposed approach completely eliminates the serial inclusion of fictitious network elements at any node of the system. The entire procedure is illustrated by a flow chart shown in Fig. 2.

For a given condition, the network should initially be simulated using EPANET 2, identifying the maximum pressuredeficient node and setting its demand as zero. This process should be implemented repeatedly until all the nodes reach the condition $H_{avl} \ge H_{req}$. It should be noted here that all non-zero nodes could deliver the design demand. Then, increase the elevation of zero-set nodes to H_{min} (ie. $EL_j + H_{min}$) and calculate the emitter coefficient to be assigned to those nodes. Next, the network is simulated again. If a negative flow takes place at any emitter-set node, then remove the emitter value of those nodes, perform DDA again and interpret the results. Now there are chances of H_{avl} going below H_{min} in some nodes as the coefficient of the emitter



Figure 9. Nodal pressure when reservoir ID 272 is disconnected (PDA).

with negative flows is set to zero. Here such nodes cannot behave as sources. Hence, if pressure in some nodes becomes less than minimum pressure, then set the zero demand again, change the nodal property as mentioned above and simulate the network. The analysis ends only if no negative flow exists and none of the non-zero demand nodes experience H_{avl} less than H_{min} . At the end of the analysis, if any nodes show negative pressure, then close the pipes incident to those nodes and simulate again to get a final solution. The procedure is illustrated further by a flow chart (Fig. 2).

3 Results and discussion

The proposed methodology was experimented with three benchmark networks. The results of example 1 and 2 were compared with SIPDA, proposed by Mahmoud et al. (2017).

3.1 Example 1

A single-fixed source-head two-loop network with six demand nodes and eight links (proposed by Ang and Jowitt, 2006, for PDA) is considered for illustrating the proposed approach (see Fig. 3). Each pipe is 1000 m long, with a Hazen– Williams coefficient of 130. The nodal demand for each node is 25 L s^{-1} . DDA shows the full delivery of design demand at the respective elevation under normal conditions. To test the proposed algorithm, three scenarios were considered: (i) the closing of pipe 3, (ii) fire demand of 50 L s^{-1} at node 2 and (iii) fire demand of 50 L s^{-1} at node 7. Table 3 provides both DDA and proposed PDA results for all three scenarios. Equation (5) is used to simulate the pressure-flow relation (equivalent to a difference between required and minimum pressures below 0.001 m if using Eq. 2) with an emitter exponent of 0.54.

DDA shows negative pressure at all the demand nodes except node 2, while pipe 3 was isolated from service (scenario 1). Node 4 was observed as the maximum negative pressure node, and its nodal demand was set to zero. Again hydraulic simulation is carried out to verify whether all nodes turned into pressure above zero. But node 6 was still facing

Table 3. Step-by-step analysis results showing nodal outflows and pressure at each level of simulation. Bracketed values denote available pressure in meters.

Demand $(L s^{-1})$ and available pressure (m)								
Simulation	Node 2	Node 3	Node 4	Node 5	Node 6	Node 7		
Pipe 3 closed condition								
1 (pipe 3	25.00	25.00	25.00	25.00	25.00	25.00		
closed)	(3.57)	(-6.14)	(-23.17)	(-19.76)	(-22.31)	(-22.06)		
2 (zero demand	25.00	25.00	0.00	25.00	25.00	25.00		
to node 4)	(5.42)	(-1.01)	(-9.21)	(-8.18)	(-9.28)	(-9.25)		
3 (zero demand	25.00	25.00	0.00	25.00	0.00	25.00		
to node 6)	(6.97)	(3.2)	(0.66)	(0.87)	(3.05)	(2.43)		
4 (set K_e)	25.00	25.00	-18.34	25.00	20.94	25.00		
to node 4 and 6	(6.82)	(2.8)	(0.00)	(0.05)	(0.00)	(-0.03)		
5 (remove K_e	25.00	25.00	Isolated	25.00	0.54	25.00		
at node 4 and	(6.94)	(3.11)	(0.00)	(0.7)	(0.00)	(0.00)		
close the pipes								
incident to the								
node)								
$50 \mathrm{Ls^{-1}}$ fire demand at no	de 2							
1 (set demand	75.00	25.00	25.00	25.00	25.00	25.00		
at node 2 to	(-0.95)	(-3.12)	(-2.21)	(-2.87)	(-3.09)	(-3.11)		
$75 \mathrm{L}\mathrm{s}^{-1}$)								
2 (set zero demand	75.00	0.00	25.00	25.00	25.00	25.00		
to node 3)	(1.45)	(0.5)	(0.6)	(0.21)	(-0.15)	(-0.16)		
3 (set zero demand	75.00	0.00	25.00	25.00	25.00	0.00		
to node 7)	(3.57)	(3.03)	(3.88)	(3.72)	(5.46)	(6.09)		
4 (change nodal	75.00	6.25	25.00	25.00	25.00	21.96		
property for	(1.16)	(0.00)	(0.38)	(-0.05)	(0.00)			
nodes 3 and 7)								
5 (change nodal property	75.00	6.81	25.00	24.06	25.00	22.26		
for node 5)	(1.17)	(0.00)	(0.41)	(0.00)	(0.00)	(0.00)		
$50 \mathrm{L}\mathrm{s}^{-1}$ fire demand at node 7								
1 (set demand	25.00	25.00	25.00	25.00	25.00	75.00		
at node 7 to	(-0.95)	(-4.66)	(-5.45)	(-6.88)	(-14.46)	(-17.56)		
$75 \mathrm{L}\mathrm{s}^{-1}$)	. ,	. ,	. ,	. /	. ,	. ,		
2 (set zero demand	25.00	25.00	25.00	25.00	25.00	0.00		
at node 7)	(5.42)	(3.88)	(5.37)	(5.01)	(6.87)	(7.44)		
3 (change nodal property	25.00	25.00	25.00	25.00	25.00	29.93		
at node 7)	(3.18)	(0.87)	(1.64)	(0.93)	(0.1)	(0.00)		

a higher pressure-deficit condition from nodes 3 to 7, and its demand was set to zero. After setting the emitter coefficient to both node 4 and 6, the hydraulic analysis shows a negative flow at node 4 and a negative pressure at node 7. By disconnecting pipes incident to node 4 and removing its K_e , the other outflows are computed. This scenario requires five demand-driven analyses to obtain PDA results. Furthermore, the same result was obtained using the SIPDA proposed by Mohmoud et al. (2017) after disconnecting incident pipes to node 4. SIPDA took three DDA runs after the addition of artificial links between network elements and five nodes.

In the next case (scenario 2), a fire demand of $50 L s^{-1}$ is created at node 2. The total demand at node 2 is changed to $75 L s^{-1}$. As this node is nearer to the source, there is more possibility to satisfy the extra demand. But DDA indicates negative pressure in all the nodes as the total demand of that node was increased by 3 times the design demand (i.e., 2 times higher than the existing demand). Nodal demand at node 3 and 7 was sequentially modified to zero after noticing negative pressure. Then, the network showed pressure greater than H_{\min} at these nodes. Hence, it is possible to partially deliver the flow to those nodes with demand set to zero. Then the emitter coefficient was set both to nodes 3

 Table 4. Step-by-step analysis results showing nodal outflows under two pressures.

Demand $(L s^{-1})$	and availal	ble pressur	e (m)			
Simulation	Node 2	Node 3	Node 4	Node 5	Node 6	Node 7
Pipe 3 closed cor	ndition					
1 (pipe	25.00	25.00	25.00	25.00	25.00	25.00
3 closed)	(38.57)	(28.86)	(11.83)	(15.24)	(12.69)	(12.94)
2 (zero demand	25.00	25.00	0.00	25.00	25.00	25.00
to node 4)	(40.42)	(33.99)	(25.79)	(26.82)	(25.72)	(25.75)
3 (zero demand	25.00	25.00	0.00	25.00	0.00	25.00
to node 6)	(41.97)	(38)	(35.66)	(35.87)	(38.05)	(37.43)
4 (change	25.00	25.00	15.75	25.00	17.39	25.00
nodal property	(39.85)	(32.42)	(21.36)	(23.32)	(22.64)	(22.64)
for nodes 4 and						
6, assign						
$K_{\rm e} = 5.8$)						
5 (change	25.00	25.00	18.14	20.47	19.88	20.04
nodal property	(40.17)	(33.32)	(23.26)	(25.34)	(24.74)	(24.93)
for nodes 5						
and 7, assign						
$K_{\rm e} = 5.8$)						
SIPDA						
$C_d = 5.8$	25.00	25.00	17.22	25.00	19.15	19.29
	(40.02)	(32.91)	(22.50)	(24.42)	(24.13)	(24.26)
Proposed approa	ch for isola	ation of lin	ks 3 and 6			
1 (pipe 3 and	25.00	25.00	25.00	25.00	25.00	25.00
6 isolated)	(38.57)	(28.86)	(14.04)	(15.24)	(1.86)	(5.41)
2 (set demand	25.00	25.00	25.00	25.00	0.00	25.00
at node 6	(40.42)	(33.99)	(25.62)	(26.82)	(26.27)	(26.27)
to zero)						
3 (set demand	25.00	25.00	25.00	25.00	0.00	0.00
at node 7	41.97	38.2	34.67	35.87	38.87	38.87
to zero)						
4 (change	25.00	25.00	25.00	25.00	14.66	16.45
nodal property	(39.99)	(32.89)	(23.02)	(24.22)	(20.57)	(21.89)
at nodes 6						
and 7, assign						
$K_{\rm e} = 5.8)$						
5 (change	25.00	25.00	20.66	21.54	15.99	17.94
nodal property	40.34	33.78	25.51	26.35	21.54	23.09
at nodes 4						
and 5, assign						
$K_{\rm e} = 5.8$)						

and 7, and the network was simulated. No negative pressure or negative flow was detected at these two nodes, but pressure at node 5 became negative. Changing nodal demand and setting the emitter coefficient at node 5 provided a final result after simulation. It can be seen that the network is able to supply full fire demand at node 2, full supply at nodes 4 and 6, and partial supply at nodes 3, 5 and 7. SIPDA provided the same result while emitter coefficient was taken to be 2500. Analysis by SIPDA necessitates addition of serial fictitious network elements to all the demand nodes as all the nodes experienced negative pressure at $50 L s^{-1}$ fire demand at node 2.

In the third scenario, a fire demand of 50 L s^{-1} at node 7 is added, and the network is simulated. Application of the proposed approach and SIPDA provided the same results.

Node ID	Elevation (m)	Demand $(m^3 h^{-1})$	Pipe no.	Length (m)	Diameter (mm)
1	165	100	1	1000	457.2
2	160	150	2	1000	508
3	155	120	3	500	355.6
4	150	120	4	1000	203.2
5	150	200	5	1000	203.2
6	155	100	6	1000	355.6
7	160	100	7	1000	152.4
8	160	330	8	1000	355.6
9	160	240	9	1000	254
			10	1000	355.6
			11	1000	152.4
			12	1000	152.4
			13	1000	152.4
			14	1000	406.4
			15	1000	406.4

Table 5. Nodal and pipe properties of multisource pumped network.

Table 6. Design demand during different time steps for multisource pumped network.

	Demand in $m^3 h^{-1}$						
Node ID	Time step 1	Time step 2	Time step 3	Time step 4			
1	20	100	60	80			
2	30	150	90	120			
3	24	120	72	96			
4	24	120	72	96			
5	40	200	120	160			
6	20	100	60	80			
7	20	100	60	80			
8	66	330	198	264			
9	48	240	144	192			

3.2 Example 2

Network 1 was used as it is for further analysis by setting reservoir elevation to 135 m instead of 100 m. The minimum and required pressures at all the demand nodes are designated as 15 and 30 m respectively. DDA indicates that the network can supply design demand from all the demand nodes at the required pressure level of 30 m. SIPDA and the proposed approach require an emitter coefficient, K_e . For demand 25 L s⁻¹ with $H_{req} = 30$ and $H_{min} = 15$ m, the emitter coefficient is obtained as 5.80 L s⁻¹ m^{-0.54}. The same value is utilized for both approaches to simulate the behavior of the network under isolation of link 3.

PDA was carried out by the proposed approach. DDA needs to be run five times, and results obtained are presented in Table 4. The proposed method indicates full supply of design demand at nodes 2 and 3, while the remaining nodes are able to supply only partial demand. For the same case study, SIPDA makes partial supply at nodes 4, 6 and 7, while



Figure 10. Actual outflow against design demand when there is no supply from reservoir ID 270.

recorded pressure is in between H_{min} and H_{req} . Though the pressure at node 5 is below H_{req} , SIPDA indicates the full supply of demand instead of partial supply. The SIPDA result at this node violates the assumption of partial supply in between minimum and required pressure.

Furthermore, by closing two links, 3 and 6, the network was simulated, and DDA shows pressure below minimum at nodes 4, 5, 6 and 7. By applying proposed approach, actual demands and pressures were evaluated and presented in Table 4. Under the failure condition in pipes 3 and 6, the network is able to supply full design demand at nodes 2 and 3. The remaining nodes are able to supply partial demand only.

3.3 Example 3

A multisource pumped water distribution network presented by Jinesh Babu and Mohan (2012) was considered for further testing of the proposed approach. Figure 4 shows the network layout, consisting of two pumps with the capacity of 125 kW each, instead of 125 hp, considered by Jinesh Babu and Mohan (2012), and was designed to deliver two-thirds of total demand. These two pumps, P1 and P2, pump the water from two sources, S1 and S2, respectively, whose elevations are 100 m each. The remaining one-third of total demand is drawn from reservoir, S3, whose elevation is 200 m, and one flow control valve is provided between reservoir S3 and node 7 in order to control the flow to one-third of total demand. A demand pattern with four intervals is considered with demand factors (DFs) of 0.2, 1.0, 0.6 and 0.8, which represent time intervals of 0.00 to 6.00, 6.00 to 12.00, 12.00 to 18.00 and 18.00 to 24.00 h respectively. The optimal speed of pumps for the respective time interval needs to be set to 0.584, 1.0, 0.842 and 0.927. The Hazen-Williams roughness coefficient of 130 is assumed for all the pipes. As Jinesh Babu and Mohan (2012) did not specify the upper and

Nodal outflow $(m^3 h^{-1})$ and available pressure (m)										
Time step	N1	N2	N3	N4	N5	N6	N7	N8	N9	Total flow
1	4.26	18.17	20.78	24	40	17.26	12.79	41.82	30.38	209.46
	15.86	20.93	26.49	30.86	30.86	26.44	21.57	21.44	21.43	
2	33.82	99.66	120	40.84	68.17	100	91.07	266.61	192.22	1012.39
	17.01	22.04	31.33	17.02	17.04	30.27	27.62	25.11	24.94	
3	0	45.5	65.63	68.71	114.49	53.81	43.29	133.79	96.73	621.94
	13.79	19.24	27.64	28.76	28.75	27.26	23.2	22.26	22.18	
4	0	52.68	90.02	86.83	144.66	73.05	61.6	183.49	132.54	833.58
	12.51	18.27	28.32	27.46	27.45	27.67	24.24	22.65	22.52	

 Table 7. Nodal outflows under pump 1 failure condition for multisource pumped network.

Table 8. Total outflow from Modena-network-selected links' isolation condition.

Link ID	Pipe diameter (mm)	Deficit nodes as per DDA	Total outflow LPS
11	100	1	406.9321
22	200	63	400.8348
50	150	26	404.3639
68	200	115	391.542
100	150	57	390.9427
157	300	180	362.8878
158	300	182	361.7787
224	125	11	406.7551
242	125	14	405.1062
250	100	0	406.9399
291	350	245	277.6133
292	350	247	264.385

lower service pressure limit to the network, it is assumed in the present study that the required and minimum pressures needed for each demand node as 30 and 15 m respectively. Table 5 presents the pipe and nodal properties of the network. Table 6 shows the required nodal outflows at four time steps.

The pump 1 failure case was analyzed to examine the proposed approach. The results of EPS analysis for four time steps are presented in Table 7. This scenario produces partial flow at several nodes in all time steps. It is to be noted that in the first and second time steps, all nodes supply some water, whereas in the next two time steps, node 1 is unable to deliver even partial flow. Two nodes at time steps 1 and 2 indicates pressure greater than H_{req} with full supply conditions, and all remaining nodes have an H_{avl} between H_{min} and H_{req} , while in case of time step 3 and 4 no nodes were noticed where H_{avl} is greater than H_{req} . This indicates that the proposed approach is able to simulate the pressure-based flow when the network is energized by pumps, apart from gravity flow by the reservoir. The network is able to supply

71.17%, 69.34%, 70.99% and 71.37% of its total design demand at respective time steps. But it should be noted here that the drop in supply under failure of the component is not uniform in all the nodes. While optimizing the network, the various components of the network should be sized in such a way that, to a possible extent, all nodes are affected uniformly under failure of any component so that equity can be maintained under failure scenarios. PDA is becoming very important in achieving this.

3.4 Example 4

To examine the applicability of proposed approach on a large size benchmark network, a Modena network (MOD) given by the Centre for Water Systems at the University of Exeter (Wang et al., 2014) is considered. Its layout is shown in Fig. 5, and it consists of 317 pipes, 268 demand nodes and four reservoirs with a fixed head in the range of 72.0 to 74.5 m. In the present work, the layout, its diameter and a Hazen-Williams roughness coefficient of 130 are considered, as they are given by the network. The minimum and required pressures are assumed to be 10 and 20 m respectively. Supply from reservoir ID 272 is stopped fully by isolation of a pipe connecting the reservoir and nearest node. DDA indicates a pressure deficit (i.e., below H_{req}) in 171 demand nodes. Using the EPANET toolkit, the proposed approach was implemented, and the results are presented in Fig. 6. Actual outflow versus the design demand plot (Fig. 6) shows the number of full supply and partial supply nodes. The trajectory of points lying along the diagonal line indicates full supply nodes, and points lying below the diagonal line denote partial supply against design demand. It is found from PDA that the network is able to supply 89.1% of total demand while supply from reservoir ID 272 is ceased. Out of 268 nodes, 90 nodes are able to make partial supply to the consumers, and the remaining nodes could make the design supply. Figure 7 presents the distribution of nodal pressure under the no-component failure condition. The DDA indicates that pressure at all the nodes is above H_{req} and hence

Furthermore, supply from reservoir ID 270 is closed, and the proposed approach was applied. It can be noticed that DDA showed that 232 nodes are pressure-deficient nodes. In the absence of supply from reservoir ID 270, the network is able to supply 78.46 % of total design demand. From Fig. 10, it is possible to notice the large number of supply nodes becoming affected in the absence of reservoir ID 270; 49 % of total nodes could deliver full design supply, and the remaining nodes could make only partial supply. Table 8 presents the total outflow from the network obtained by isolation of selected pipes. It is evident from the results that the proposed approach is able to find the nodal outflow under any pipe failure condition, apart from the pipe connecting the source.

4 Conclusions

Pressure-driven analysis (PDA) of the water distribution network estimates realistic outflow at all demand nodes while the network is under pressure-deficient conditions. Use of available network components like the reservoir, valves and emitter to simulate pressure-based outflow is found to be a simple approach, as it could be implemented easily for small networks without a change in the source code of commercial software. But the major bottleneck in adopting such an approach is that a large number of artificial components needs to be added to either all demand nodes or deficient nodes. This increases the complexity of the network configuration and also the burden to the computational part. The proposed approach does not utilize the artificial components other than emitter. The emitter is not a physical component to be added at the demand nodes. Instead it requires an appropriate coefficient to activate the emitter and estimate the outflow based on available pressure at the node. By changing the nodal properties to those nodes categorized as pressure deficit, the pressure-based outflow is able to evaluate by proposed iterative approach using the emitter option alone. From the analysis of the results, it is evident that the proposed approach can be easily implemented for various pressure limits.

Data availability. The data for example network 4 is available at the following link http://emps.exeter.ac.uk/engineering/research/cws/resources/benchmarks/design-resiliance-pareto-fronts/ (Wang et al., 2014).

Author contributions. All authors made equal contributions to developing the algorithm and its application to example problems and writing the paper.

Competing interests. The authors declare that they have no conflict of interest.

Acknowledgements. The authors are grateful to the anonymous reviewers whose comments helped in improving the quality of the paper significantly.

Edited by: Luuk Rietveld Reviewed by: two anonymous referees

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